Uncertainty quantification and the method of Lagrangian Descriptors

Makrina Agaoglou,[1] Ana M. Mancho,[2] Guillermo García-Sánchez,[3] and Stephen Wiggins[4]

[1] *Departamento de Matemática Aplicada a la Ingeniería Industrial, E.T.S. Ingenieros Industriales, Universidad Politécnica de Madrid, Madrid, Spain.*

[2] *Instituto de Ciencias Matematicas,CSIS, C/Nicolas Cabrera 15, Campus Cantoblanco, Madrid, 28049, Spain*

[3] *Escuela Técnica Superior de Ingenieros de Telecomunicación, Universidad Politécnica de Madrid, Av. Complutense, 30, Madrid,28040,Spain*

[4] *School of Mathematics, University of Bristol, Fry Building, Woodland Road, Bristol, BS8 1UG, United Kingdom.*

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In this talk, we will present a new uncertainty quantification measure appropriate for quantifying the performance of models in assessing for example the origin or source of a given observation. We have noticed that in a neighborhood of the observation this uncertainty measure is related to the invariant dynamical structures of the model such as hyperbolic trajectories and their stable and unstable manifolds